

$$\begin{aligned}
\nabla \cdot (\vec{a} \cdot \vec{b}) &= \delta_{ij} a_i b_j + \delta_{ji} a_j b_i \\
\vec{a} = (a_1, a_2, a_3) &\quad \vec{a} \cdot \vec{b} = a_1 b_1 + a_2 b_2 + a_3 b_3 \\
\vec{b} = (b_1, b_2, b_3) &\quad \vec{a} \cdot \vec{b} = a_i b_j \quad \nabla \vec{a} = \frac{\partial}{\partial x^i} a_i \hat{x}^i \\
&\quad \nabla \cdot (\vec{a} \cdot \vec{b}) = \delta_{ij} \frac{\partial}{\partial x^i} a_i b_j \\
&\quad \nabla \vec{a} = \frac{\partial}{\partial x^i} a_i \hat{x}^i \quad \nabla \cdot (\vec{a} \cdot \vec{b}) = \delta_{ij} \frac{\partial}{\partial x^i} a_i b_j \\
&\quad \nabla \vec{a} = \frac{\partial}{\partial x^i} a_i \hat{x}^i \quad \frac{\partial}{\partial x^i} a_i b_j \\
&\quad \nabla \cdot (\vec{a} \cdot \vec{b}) = \nabla \cdot (\vec{a} \cdot a_i \hat{x}^i) = b_j \frac{\partial}{\partial x^j} a_i + a_i \frac{\partial}{\partial x^j} b_j \\
&\quad = \delta_{ij} a_i a_j \quad = \vec{b} \cdot (\nabla \cdot \vec{a}) + (\vec{a} \cdot \nabla) \vec{b} \\
&\quad (\vec{a} \cdot \nabla) \vec{a} + \vec{a} (\vec{a} \cdot \nabla) \quad \nabla \cdot (\vec{a} \cdot \vec{b}) = a_i \frac{\partial}{\partial x^i} a_i + b_i \frac{\partial}{\partial x^i} a_i \\
&\quad = a_i \frac{\partial}{\partial x^i} a_i + \cancel{a_j \frac{\partial}{\partial x^j} a_i} \quad = a(\nabla \cdot \vec{b}) + (\vec{b} \cdot \nabla) a \\
&\quad \cancel{a_j \frac{\partial}{\partial x^j} a_i} \quad \nabla \cdot (\vec{a} \cdot \vec{b}) = 4(\nabla \cdot \vec{a}) + (\vec{a} \cdot \nabla) \vec{a} \\
&\quad a_i \frac{\partial}{\partial x^j} b_i + b_i \frac{\partial}{\partial x^j} a_i \\
\vec{a} \times \vec{b} &= \begin{vmatrix} \hat{x}^1 & \hat{x}^2 & \hat{x}^3 \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \hat{x}^1 (a_2 b_3 - a_3 b_2) + \hat{x}^2 (a_3 b_1 - a_1 b_3) + \hat{x}^3 (a_1 b_2 - a_2 b_1) \\
&\quad \cancel{\epsilon_{ijk}} a_i b_j \quad \epsilon_{ijk} \\
&\quad \vec{a} \times (\vec{b} \times \vec{c}) \quad \epsilon^{231} a_2 b_3 + \epsilon^{321} a_3 b_2 \quad \epsilon^{ijk} a_i + \\
&\quad \epsilon_{ikm} a^k \epsilon_{ijk} b_i c_j \quad \vec{a} \cdot (\vec{b} \times \vec{c}) \quad \vec{b} \cdot (\vec{c} \times \vec{a}) \quad \epsilon^{ijk} a_i + \\
&\quad \epsilon_{ikm} \epsilon_{ijk} a^i b_i c_j \quad \delta_{ki} a_i \epsilon_{ijk} b_i c_j \quad \delta_{ki} b_i \epsilon_{ijk} c_i a_j \quad \epsilon^{ijk} a_i + \\
&\quad \cancel{\epsilon_{ikm} \epsilon_{ijk}} \quad \cancel{a^i b_i c_j} \quad \cancel{a_j b_i c_i} \quad \cancel{a_1 a_2 a_3} \\
&\quad \cancel{\epsilon_{ikm} \epsilon_{ijk}} \quad \cancel{a^i b_i c_j} \quad \cancel{a_j b_i c_i} \quad \cancel{a_1 a_2 a_3} \\
&\quad \delta^{ij} a_i \cancel{b_j c_k} + \delta^{ij} a_i b_j c_k \quad a_i = \delta^{ij} a_j \quad (\delta^{jk} - 1) \\
&\quad a_i (\delta^{ij} c_k - \delta^{jk} b_i) \quad \epsilon_{ijk} a_i b_j = \cancel{a_i b_j - a_j b_i} \\
&\quad \delta^{ij} a_i (c_j b_k - c_k b_j) \quad \cancel{\delta^{ijk} (\delta^{jk} a_i - \delta^{ik} a_j)} \\
&\quad \delta^{ijk} \delta_{ilm} = (\delta_{il} \delta_{jm} - \delta_{im} \delta_{jl}) \\
&\quad \epsilon_{ijk} \delta_{ilm} = \begin{vmatrix} l & m & k \\ \delta_{il} & \delta_{jl} & \delta_{kl} \\ m & \delta_{im} & \delta_{jm} \\ n & \delta_{in} & \delta_{jn} \end{vmatrix} \quad \delta_{ijk} \delta_{ilm} = \begin{vmatrix} l & m & k \\ \delta_{il} & \delta_{jl} & \delta_{kl} \\ m & \delta_{im} & \delta_{jm} \\ n & \delta_{in} & \delta_{jn} \end{vmatrix} \\
&\quad \delta_{ilm} \delta_{ilm} = \begin{vmatrix} l & m & k \\ \delta_{il} & \delta_{ml} & \delta_{kl} \\ m & \delta_{im} & \delta_{ml} \\ n & \delta_{in} & \delta_{ml} \end{vmatrix} \quad \delta_{ilm} \delta_{ilm} = \cancel{\delta_{ilm} \delta_{ilm}} \\
&\quad \delta_{ilm} \delta_{ilm} = \cancel{\delta_{ilm} \delta_{ilm}} \quad \delta_{ilm} \delta_{ilm} = \cancel{\delta_{ilm} \delta_{ilm}}
\end{aligned}$$

$$\begin{aligned}
&\delta_{ii'} \delta_{jj'} \delta_{kk'} + \delta_{ij'} \delta_{kj'} \delta_{ik'} + \delta_{ij'} \delta_{jk'} \delta_{ki'} \\
&- (\delta_{ki'} \delta_{jj'} \delta_{ik'} + \delta_{kj'} \delta_{ik'} \delta_{jj'} + \delta_{ji'} \delta_{ij'} \delta_{kk'}) \quad \epsilon_{ijkl} \epsilon_{i'j'k'l'} = \epsilon_{ijkl} \epsilon_{i'j'k'l'} = \\
&3 (\delta_{ik'} (\delta_{ii'} \delta_{jj'} - \delta_{jj'} \delta_{ii'})) \quad i \quad j \quad k \quad l \quad i \quad j \quad k \quad l \\
&+ \delta_{ik'} (\delta_{ij'} \delta_{kj'} - \delta_{kj'} \delta_{ij'}) \quad \stackrel{3-2=1}{\cancel{\delta_{ik'}}} \quad \stackrel{i=1,2,3,4}{\cancel{\delta_{ij'}}} \quad \stackrel{j'=1,2,3,4}{\cancel{\delta_{kj'}}} \quad \stackrel{k'=1,2,3,4}{\cancel{\delta_{ik'}}} \quad \stackrel{l'=1,2,3,4}{\cancel{\delta_{kl'}}} \quad \delta_{kl} \\
&+ \delta_{jk'} (\delta_{ij'} \delta_{ki'} - \delta_{ki'} \delta_{ij'}) \quad \stackrel{4-2=2}{\cancel{\delta_{jk'}}} \quad \stackrel{i=1,2,3,4}{\cancel{\delta_{ij'}}} \quad \stackrel{j=1,2,3,4}{\cancel{\delta_{ki'}}} \quad \stackrel{k=1,2,3,4}{\cancel{\delta_{jk'}}} \quad \stackrel{l=1,2,3,4}{\cancel{\delta_{kl}}} \\
&\epsilon_{ij} \delta_{ij'} = \begin{matrix} i & j \\ i' & j' \end{matrix} \quad \delta_{ij'} \quad \text{指标数不同导致的.} \\
&\epsilon_{ij} \delta_{ij'} = \begin{matrix} i & j \\ j' & j \end{matrix} = \delta_{ij'} \quad \frac{d\vec{r}}{dt} = \vec{e} = \frac{B}{B} \vec{e} \\
&\epsilon_{ij} \delta_{ij'} = \begin{matrix} i & j \\ i & j' \end{matrix} = \delta_{ij'} \quad \frac{d\vec{r}}{B} = \frac{d\vec{r}}{B} \vec{e}
\end{aligned}$$